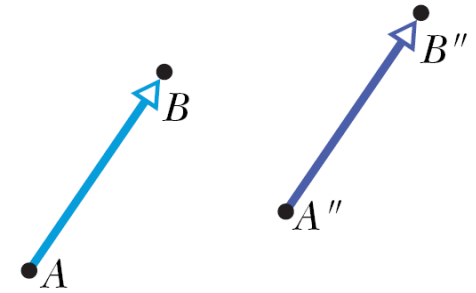
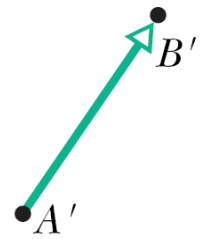


# Chapter 3 Vectors

## Vectors and Scalars

- A **vector** has magnitude as well as direction.
- A **vector quantity** is a quantity that has both a magnitude and a direction and thus can be represented with a vector, eg, displacement, velocity, acceleration.
- A **scalar** has magnitude but no direction, eg, temperature, energy, mass, time.



(a)

● **Displacement vectors** AB, A'B', A''B'' represent the same *change of position*.

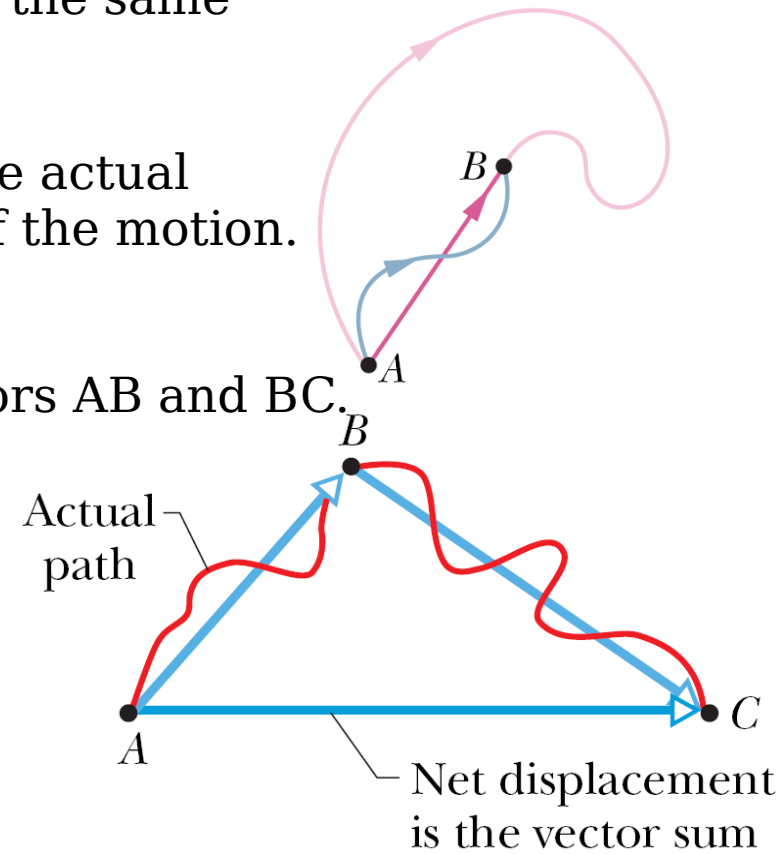
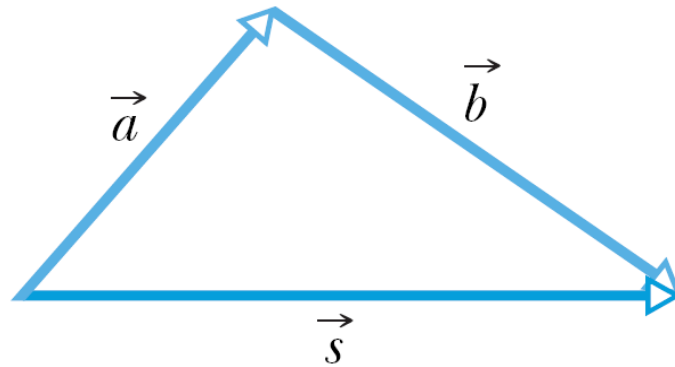
● The displacement vector tell us nothing about the actual path that the particle take, but the overall effect of the motion.

## Adding Vectors Geometrically

● AC is the **vector sum** (or **resultant**) of the vectors AB and BC. This sum is not the usual algebraic sum.

● Vector equation

$$\vec{s} = \vec{a} + \vec{b}$$



● The symbol  $+$  has different meanings for vectors than it does in the usual algebra because it involves both magnitude *and* direction.

● 2 important properties:

(1) the order of addition does not matter,

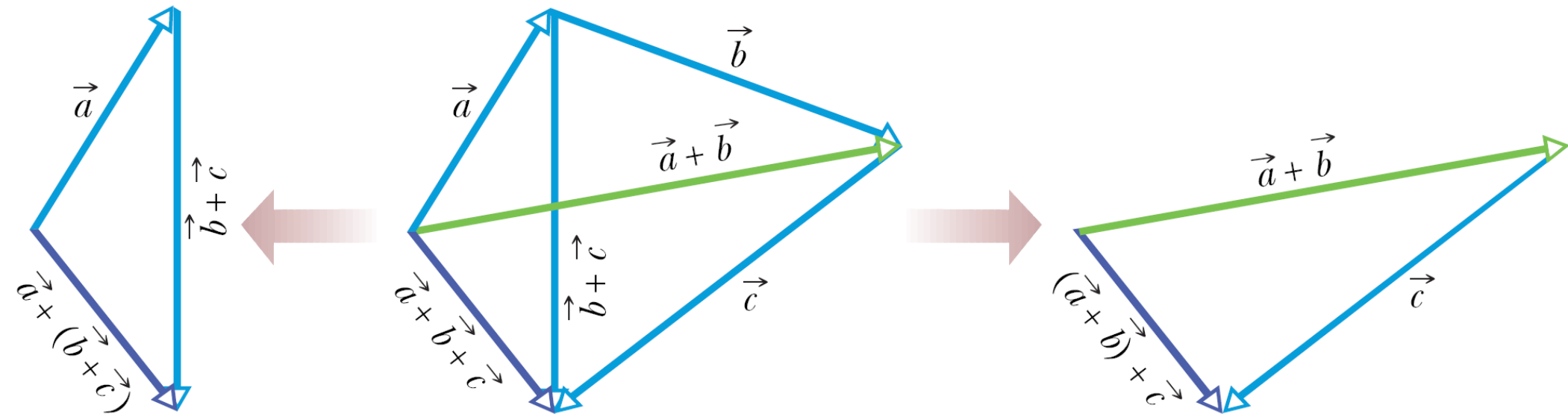
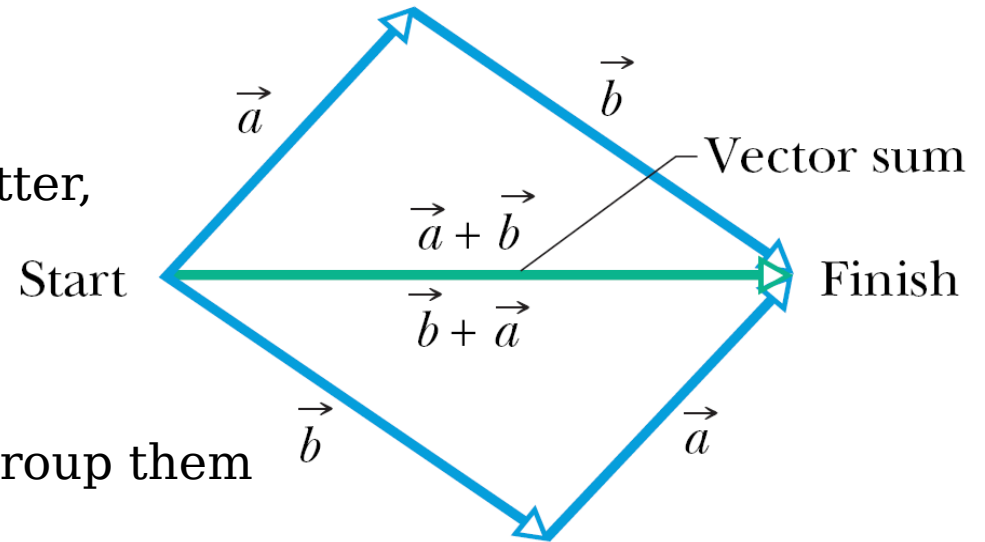
$$\vec{a} + \vec{b} = \vec{b} + \vec{a}$$

(commutative law)

(2) for more than 2 vectors, we can group them in any order as we add them,

$$(\vec{a} + \vec{b}) + \vec{c} = \vec{a} + (\vec{b} + \vec{c})$$

(associative law)

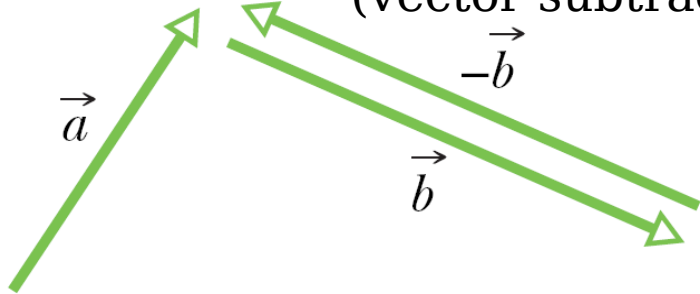


• The vector  $-\vec{b}$  is a vector with the same magnitude as  $\vec{b}$  but the opposite direction.

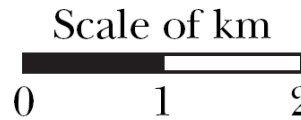
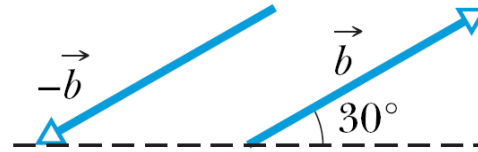
• adding  $-\vec{b}$  has the effect of subtracting  $\vec{b}$ .

$$\vec{d} = \vec{a} - \vec{b} = \vec{a} + (-\vec{b}) \Rightarrow \vec{d} + \vec{b} = \vec{a}$$

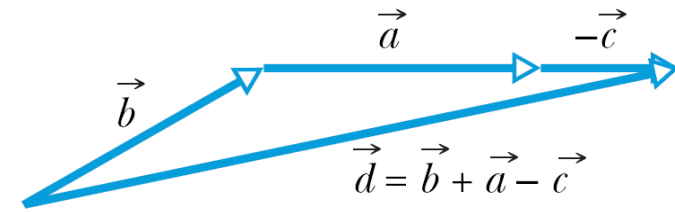
(vector subtraction)



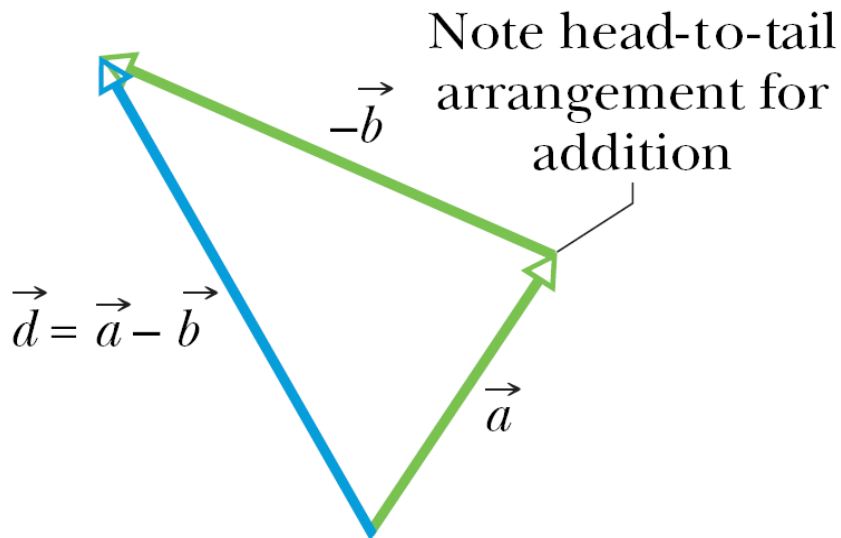
(a)



(a)



(b)



(b)

# Components of Vectors

- A **component** of a vector is the projection of the vector on an axis.

*x component*: the projection of a vector on an x axis

*y component*: the projection of a vector on an y axis

- **Resolving the vector**: the process of finding the components of a vector

- A component of a vector has the same direction (along an axis) as the vector.

$$a_x = a \cos \theta, \quad a_y = a \sin \theta$$

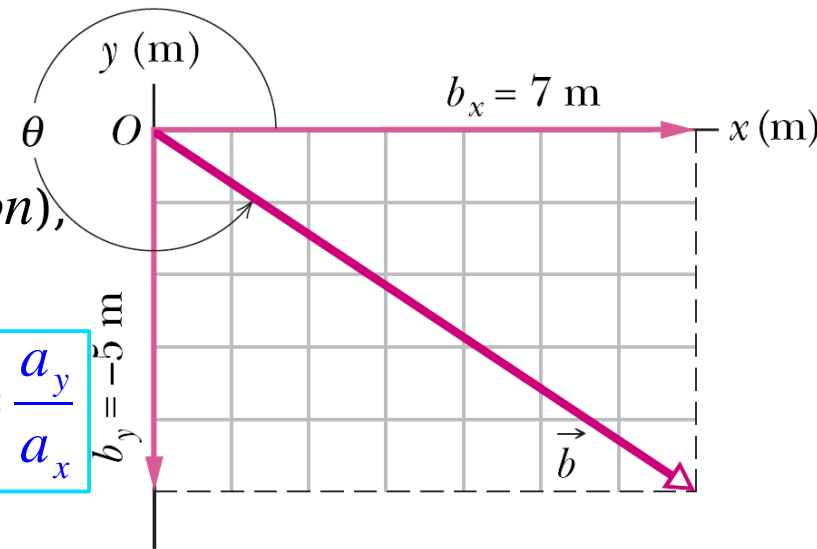
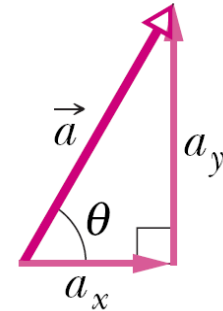
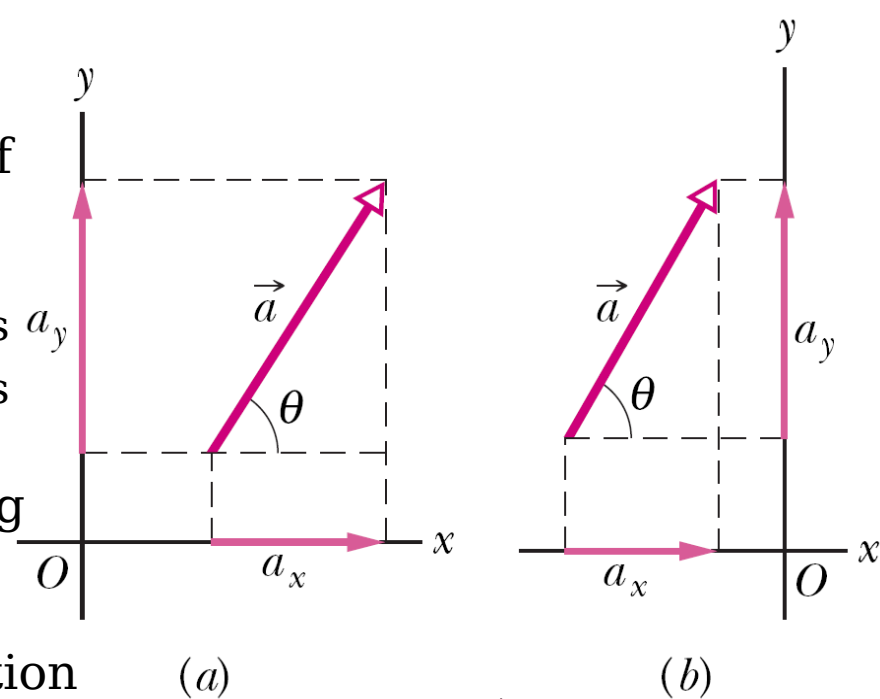
$\theta$  is the angle that the vector  $\vec{a}$  makes with the positive direction of the  $x$  axis,  $a = |\vec{a}|$ .

- Reconstruct a vector from its component.

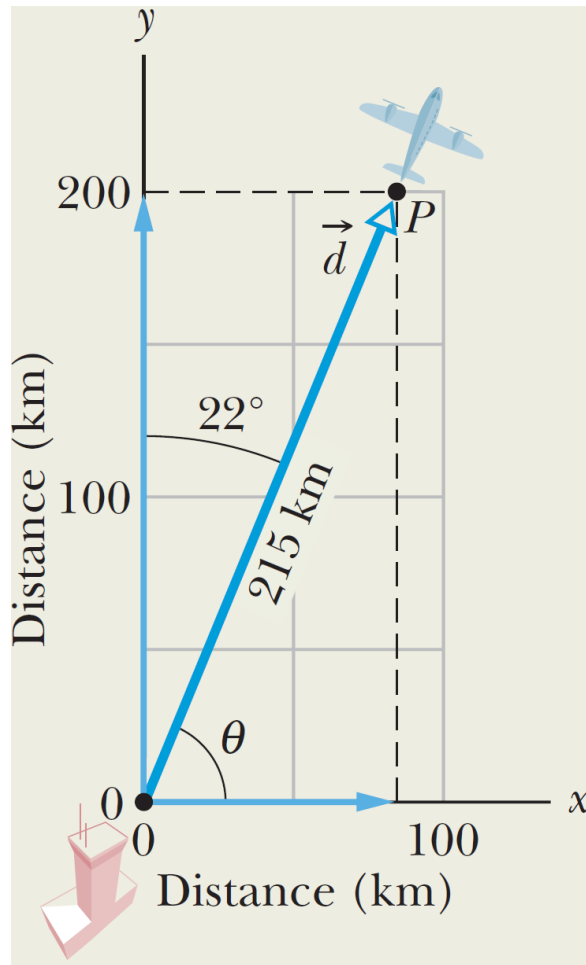
- $\vec{a}$  is determined by  $a_x$  and  $a_y$  (*component notation*), or by  $a$  and  $\theta$  (*magnitude-angle notation*).

- For transformation

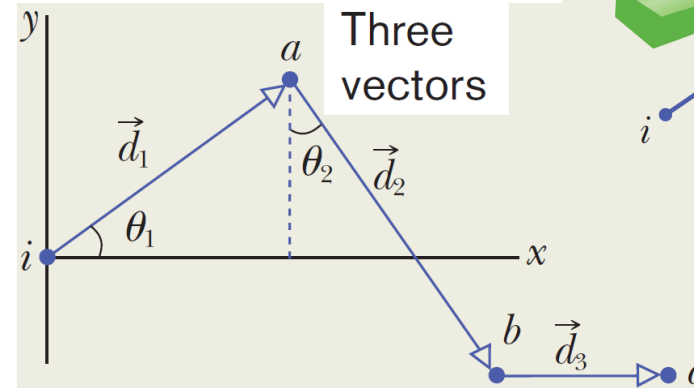
$$a = \sqrt{a_x^2 + a_y^2}, \quad \text{and} \quad \tan \theta = \frac{a_y}{a_x}$$



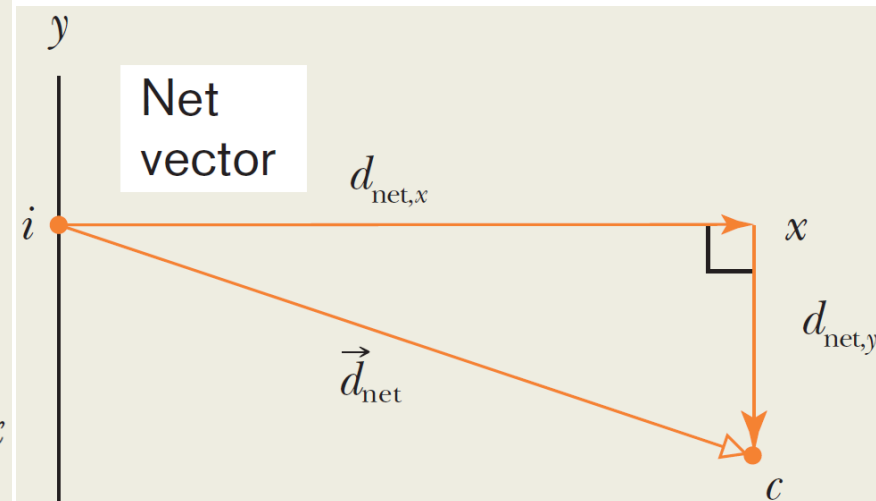
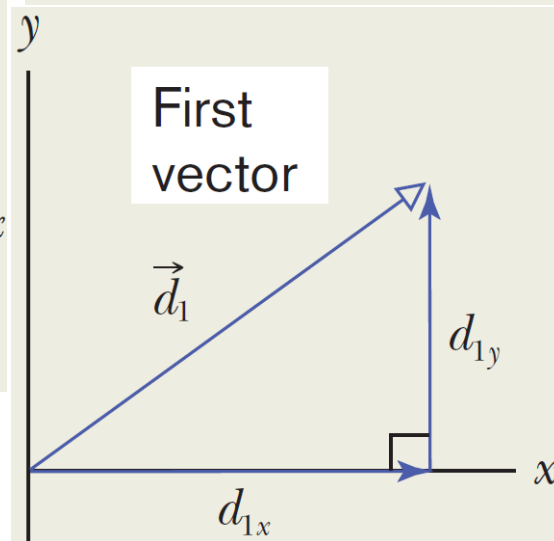
● For 3D, we need a magnitude and 2 angles ( $a$ ,  $\theta$ ,  $\phi$ ) or 3 components ( $a_x$ ,  $a_y$ ,  $a_z$ ) to specify a vector.



Problem 3-2



Problem 3-3



## Angles — Degrees and Radians

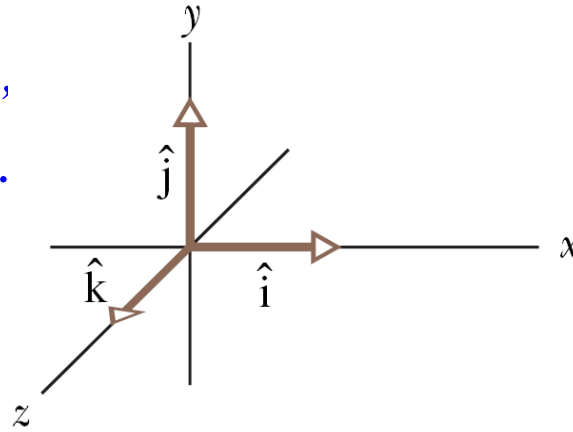
$$360^\circ (\text{degree}) = 2\pi (\text{radian}) \quad \text{Ex: } 40^\circ = 40^\circ \times \frac{2\pi}{360^\circ} = 0.70 (\text{rad})$$

## Unit Vectors

● A **unit vector** is a vector that has a magnitude of exactly 1 and points in a particular direction.

● use **right-handed coordinate system**

Example of usage:  $\vec{a} = a_x \hat{i} + a_y \hat{j}$ ,  
 $\vec{b} = b_x \hat{i} + b_y \hat{j}$ .



**vector components:**  $a_x \hat{i}$ ,  $a_y \hat{j}$

**scalar components:**  $a_x$ ,  $a_y$ .

Example:  $\vec{d} = -(2.6 \text{ km}) \hat{i} + (0.025 \text{ km}) \hat{j} + (3.9 \text{ km}) \hat{k}$

## Adding Vectors by Components

● Decompose

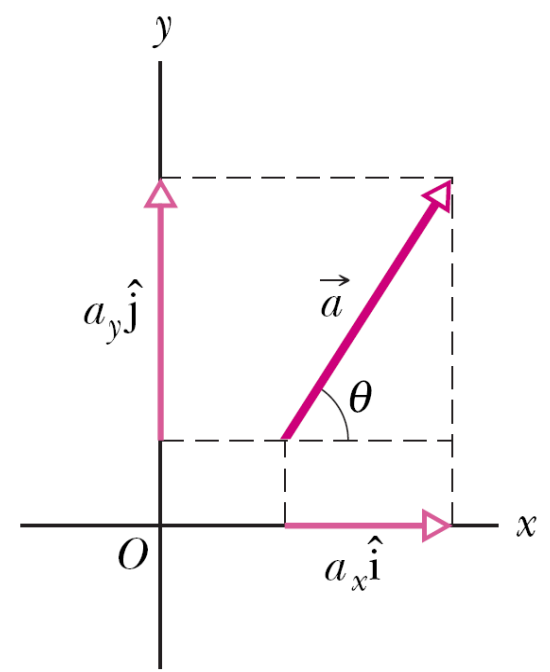
$$\vec{r} = \vec{a} + \vec{b}$$

into

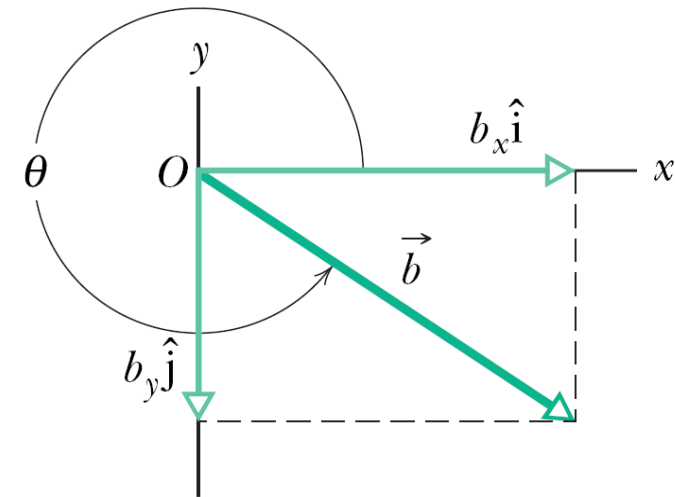
$$r_x = a_x + b_x$$

$$r_y = a_y + b_y$$

$$r_z = a_z + b_z$$



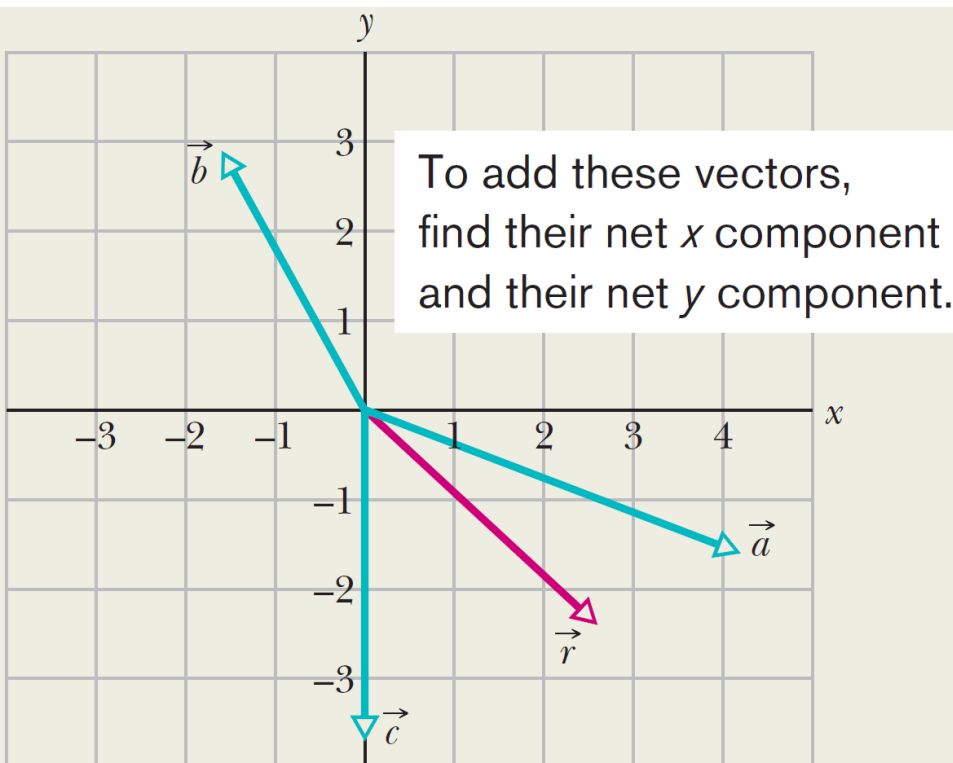
(a)



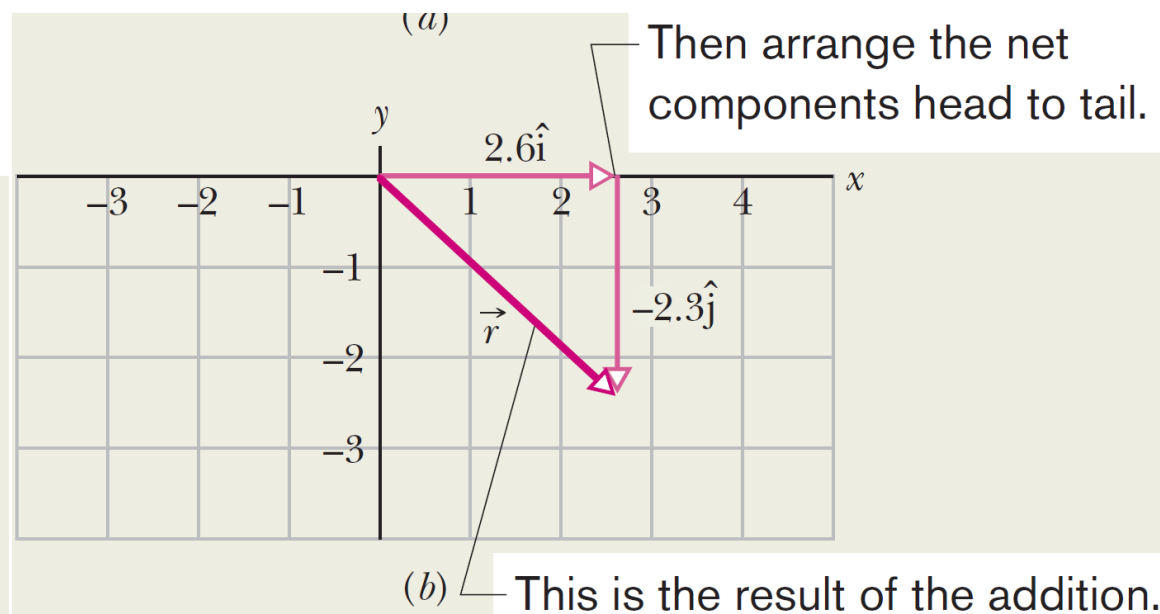
(b)

- 2 vectors must be equal if their corresponding components are equal.
- add 2 vectors, we must
  - (1) resolve the vectors into their scalar components;
  - (2) combine these scalar components, axis by axis, to get the components of the sum;
  - (3) combine the components to get the sum vector.
- This procedure also applies to vector subtractions:

$$\begin{aligned}
 \vec{d} &= \vec{a} - \vec{b} = \vec{a} + (-\vec{b}) & \Rightarrow & \begin{aligned} d_x &= a_x - b_x \\ d_y &= a_y - b_y \\ d_z &= a_z - b_z \end{aligned} \\
 &= d_x \hat{i} + d_y \hat{j} + d_z \hat{k}
 \end{aligned}$$



problem 3-4



## Vectors and the Laws of Physics

- an infinite number of different pairs of components of a vector
- Which is the right pair of components?

Ans: they are all equally valid because each pair gives a different way of describing the same vector.

- the relation:  $a = \sqrt{a_x^2 + a_y^2} = \sqrt{a_x'^2 + a_y'^2}$  and  $\theta = \theta' + \phi$

- freedom in choosing a coordinate system

- also true of the relation of physics:  
independent of the choice of coordinate system

- use the language of vector to present the laws of physics for its simplicity and richness.

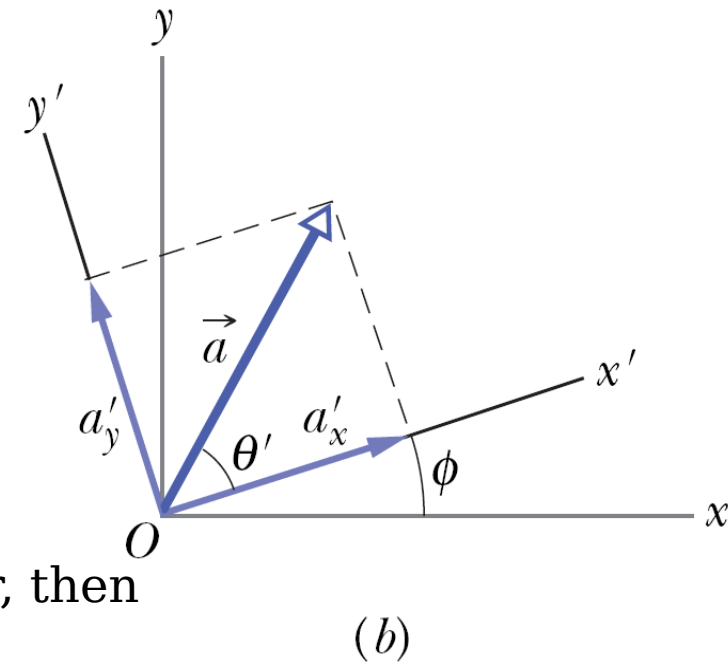
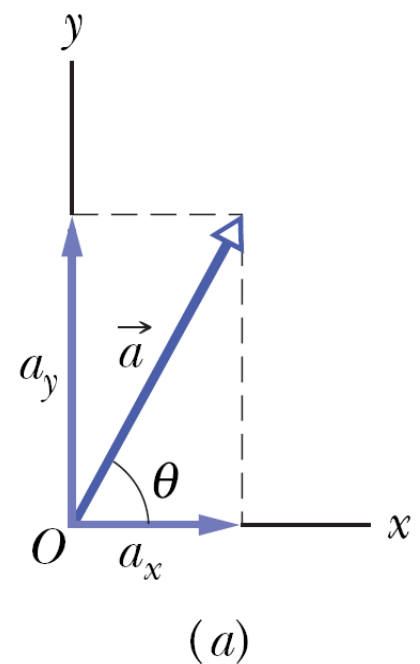
## Multiplying Vectors

- 3 ways in which vectors can be multiplied:

(1) **Multiplying a Vector by a Scalar**:  $s$  is a scalar, then

$$\vec{b} = (s)(\vec{a}) = s\vec{a}$$

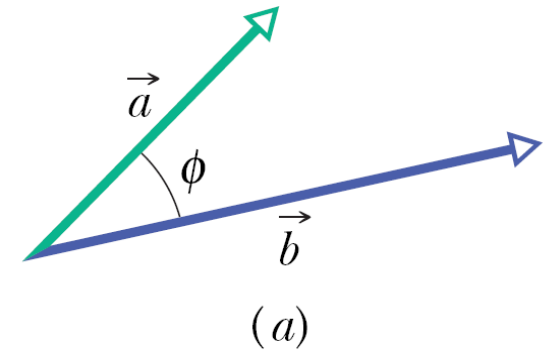
$$\vec{c} = (1/s)(\vec{a}) = \vec{a}/s$$



## (2) **Multiplying a Vector by a Vector:**

(2a) **Scalar Product:** its result is a scalar;

(2b) **Vector Product:** its result is a vector.



### **The Scalar Product** (also **Dot Product**)

- The **scalar product** of 2 vectors is defined as

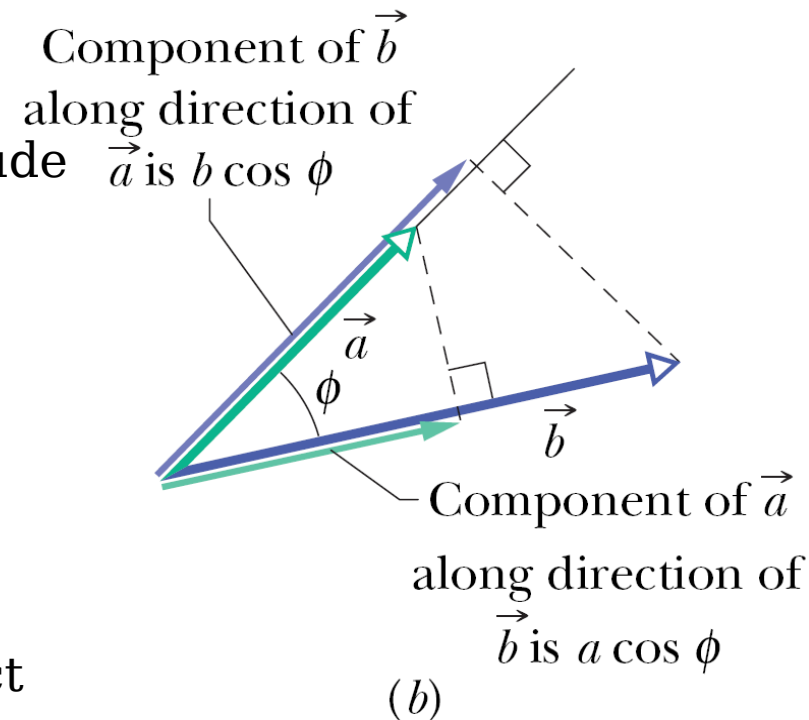
$$\vec{a} \cdot \vec{b} = a b \cos \phi$$

where  $a$  is the magnitude of  $\vec{a}$ ,  $b$  is the magnitude of  $\vec{b}$ , and  $\phi$  is the angle between  $\vec{a}$  and  $\vec{b}$ .

- The angle  $\phi$  and  $360^\circ - \phi$  is the same for the scalar product.
- $\phi = 0$  gives the scalar product its maximum;  
 $\phi = 90^\circ$  makes the scalar product be 0.

- A scalar product can be regarded as the product of 2 quantities:

- (1) the magnitude of one of the vectors, and
- (2) the scalar component of the 2<sup>nd</sup> vector along the direction of the 1<sup>st</sup> vector.



- The commutative law applies to a scalar product:

$$\vec{a} \cdot \vec{b} = (a \cos \phi)(b) = (a)(b \cos \phi) \Rightarrow \vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$$

- Express the vectors into their components for the scalar product

$$\vec{a} \cdot \vec{b} = (a_x \hat{i} + a_y \hat{j} + a_z \hat{k}) \cdot (b_x \hat{i} + b_y \hat{j} + b_z \hat{k})$$

use the distributive law to obtain the formula

$$\vec{a} \cdot \vec{b} = a_x b_x + a_y b_y + a_z b_z$$

## The Vector Product ( also Cross Product)

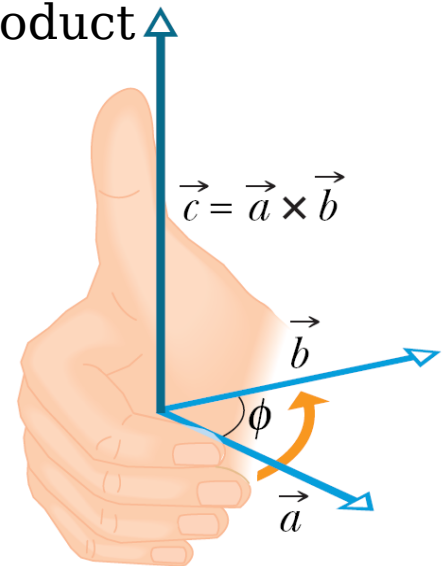
- The **vector product** of 2 vectors is defined as

$$\vec{c} = \vec{a} \times \vec{b} \quad \text{and} \quad c = a b \sin \phi$$

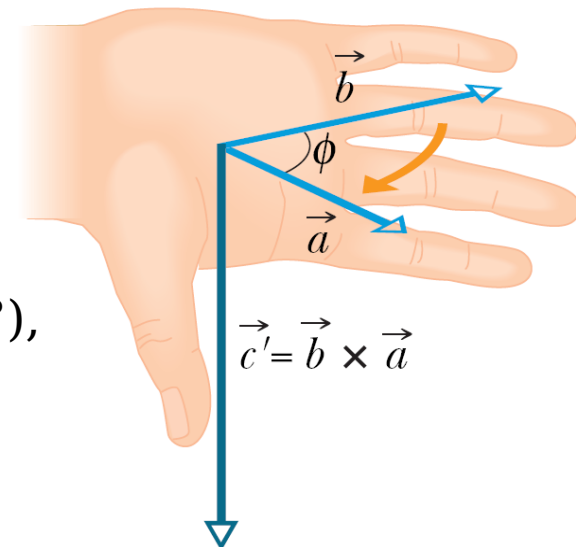
where  $\phi$  is the *smaller* angle between  $\vec{a}$  and  $\vec{b}$ .

- The direction of  $\vec{c}$  is perpendicular to the plane that contains  $\vec{a}$  and  $\vec{b}$  with a **right-hand rule**.

- If 2 vectors are parallel ( $\phi = 0$ ) or antiparallel ( $\phi = 180^\circ$ ), their cross product vanishes; if this 2 vectors are perpendicular to each other, the magnitude of their cross product is maximum.



(a)



(b)

- The order of the vector multiplication is important:

$$\vec{a} \times \vec{b} = -(\vec{b} \times \vec{a})$$

the commutative law does **not** apply to a vector product.

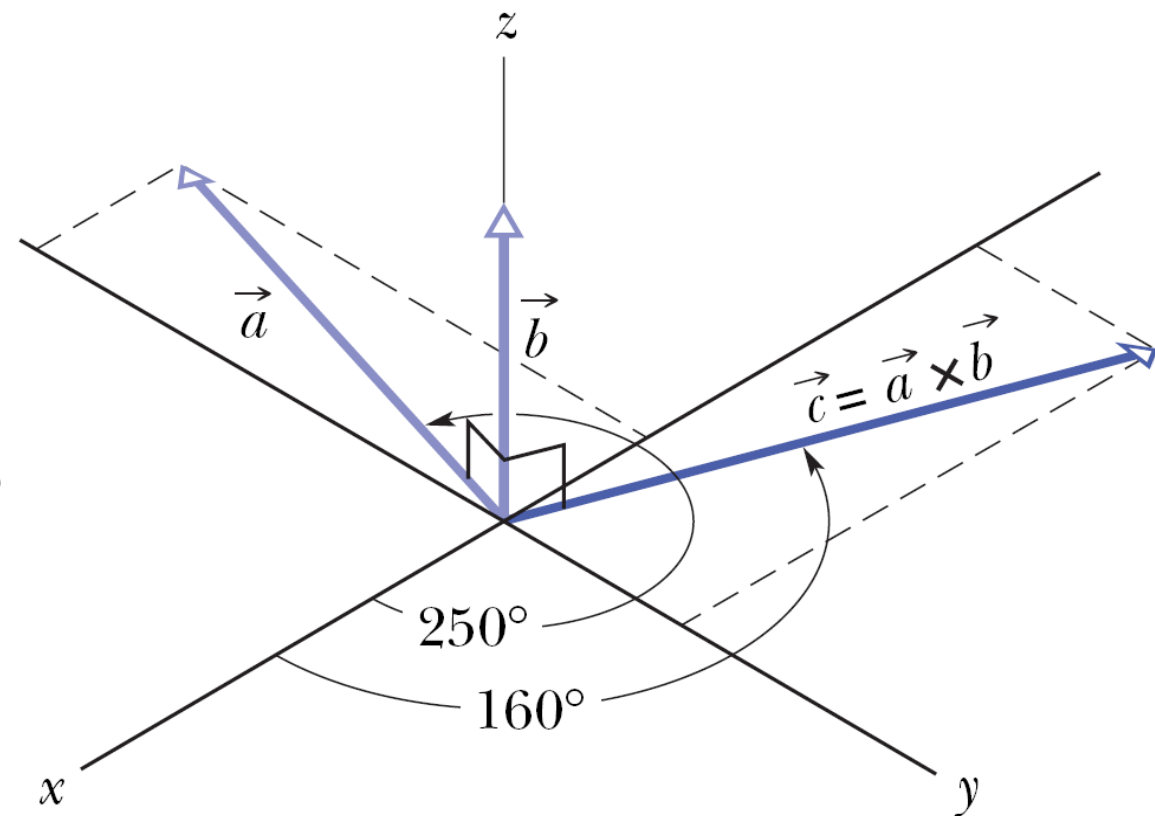
- In unit-vector notation  $\vec{a} \times \vec{b} = (a_x \hat{i} + a_y \hat{j} + a_z \hat{k}) \times (b_x \hat{i} + b_y \hat{j} + b_z \hat{k})$

Since  $a_x \hat{i} \times b_x \hat{i} = a_x b_x (\hat{i} \times \hat{i}) = 0$  and  $a_x \hat{i} \times b_y \hat{j} = a_x b_y (\hat{i} \times \hat{j}) = a_x b_y \hat{k}$

it gives

$$\vec{a} \times \vec{b} = (a_y b_z - a_z b_y) \hat{i} + (a_z b_x - a_x b_z) \hat{j} + (a_x b_y - a_y b_x) \hat{k}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}$$



Problem 3.5

Problem 3.6

Problem 3.7

The chosen problems: 26, 32, 43.