



利用不同物件偵測模型進行SAR image之 物件辨識

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報告日期: 2024/05/14

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- 相關論文
- 使用模型與結果討論
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• 資料集介紹

- 資料集選用：SARDet-100K 資料集

- 優點：

1. 將多個SAR(合成孔徑雷達) image資料集檔案彙整成一個大檔案，解決資料集大小不足問題
2. 透過彙整多個資料集，解決單一資料集訓練目標過於單一的問題

• 資料集介紹

• 資料集組成：

Dataset	Images	Instances	Target
AIR_SARShip1	501	1058	S
AIR_SARShip1	300	2040	S
HRSID	5604	16969	S
MSAR	30158	65202	A,T,B,S
SADD	883	7835	A
SAR-AIRcraft	18888	38475	A
ShipDataset	39729	50885	S
SSDD	1160	2587	S
OGSOD	18331	48589	B,H,T
SIVED	1044	12013	C
SARDet-100K	116598	245653	S,A,T,B,H,C

• Target (6類):

S代表ship,
A代表aircraft,
T代表tank,
B代表bridge,
H代表harbour,
C代表car

- 因為資料集較為龐大，模型訓練時間較長。為了縮短訓練時間，訓練時只取其中的 **5000 筆資料作為 training data**，**600 筆資料作為 validation data**

• 相關論文

• Multi-Scale Ship Detection Algorithm Based on YOLOv7 for Complex Scene SAR Images

Zhuo Chen , Chang Liu , V. F. Filaretov and D. A. Yukhimets (2023)

- 當在海面上處理多尺度船舶時，大多數現代演算法都可以成功實現船舶檢測結果。然而，在複雜場景的SAR影像中進行多尺度船舶目標偵測操作時，仍存在漏檢、誤辨識等問題。
- 此論文根據 YOLOv7 提出了一種複雜場景多尺度船舶偵測模型，稱為CSD-YOLO。
- 對 HRSID 和 SSDD 資料集的測試是為了對 CSD-YOLO 和 baseline YOLOv7 做出比較。

Table 4. Experimental results of different methods.

Model	Dataset	Precision	Recall	mAP 0.5
Faster R-CNN	SSDD	81.63	85.31	89.63
	HRSID	88.81	72.57	77.98
FCOS	SSDD	84.15	92.52	90.61
	HRSID	75.53	73.79	77.95
YOLOv3	SSDD	89.11	85.03	91.54
	HRSID	88.73	69.19	80.59
YOLOv5s	SSDD	95.14	90.01	96.28
	HRSID	84.69	75.11	83.34
YOLOv7	SSDD	91.05	84.92	93.68
	HRSID	85.52	74.58	83.64
CSD-YOLO	SSDD	95.9	95.9	98.60
	HRSID	93.22	80.42	86.10

• 相關論文

• A Lightweight SAR Image Ship Detection Method Based on Improved Convolution and YOLOv7

Hongdou Tang , Song Gao et al. (2024)

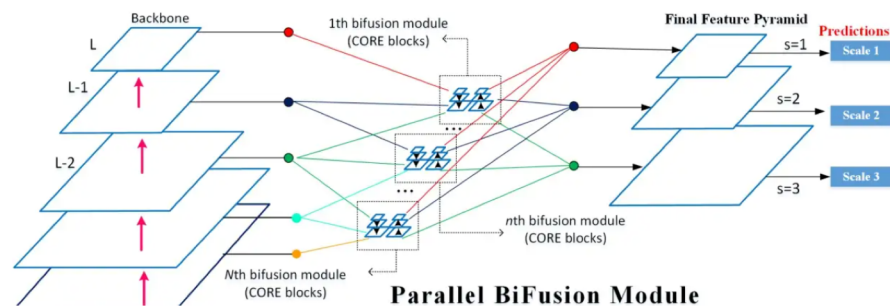
- 利用SAR影像偵測船舶目標具有廣泛的應用前景。由於SAR影像中船舶的密度大、前景和背景雜波的極度不平衡以及目標尺寸的多樣性，實現輕量且高精度的多尺度船舶目標偵測仍然是一個巨大的挑戰。
- 本文提出了一種 multi-scale receptive fields convolution block (AMMRF) 的 attention mechanism 。
- 提出了一種基於YOLOv7的新型船舶目標檢測方法——You Only Look Once SAR Ship Identification (YOLO-SARSI)，該方法獲取從高層卷積中提取的抽象語義信息，同時保留從低層卷積中提取的詳細語意資訊。

Table 1. Experimental results for the datasets. Bolded numbers indicate the best indicators. The bolded method is the one proposed in this paper.

Dataset	Model	AP ₅₀ (%)	AP _{50:95} (%)	Params (M)
HRSID	Cascade R-CNN	65.1	41.2	68.93
	Faster R-CNN	69.8	43.6	41.12
	Mask R-CNN	69.9	43.9	41.12
	SDD 300	56.5	36.8	23.75
	Swin Transformer	57.1	32.6	36.82
	RetinaNet	70.9	45.5	36.10
	YOLOv7	86.7	61.8	34.79
	YOLO-SARSI	89.3	64.0	18.43
LS-SSDD-V1.0	Cascade R-CNN	55.4	20.1	68.93
	Faster R-CNN	63.4	23.9	41.12
	Mask R-CNN	63.3	24.1	41.12
	SDD 300	32.5	10.1	23.75
	Swin Transformer	37.0	10.2	36.82
	RetinaNet	64.9	24.8	36.10
	YOLOv7	69.8	27.7	34.79
	YOLO-SARSI	73.7	28.5	18.43

- 使用模型

- YOLOv7
- YOLOv7x
- PRB-FPN (取代YOLO中backbone，特別適用於小物件偵測)



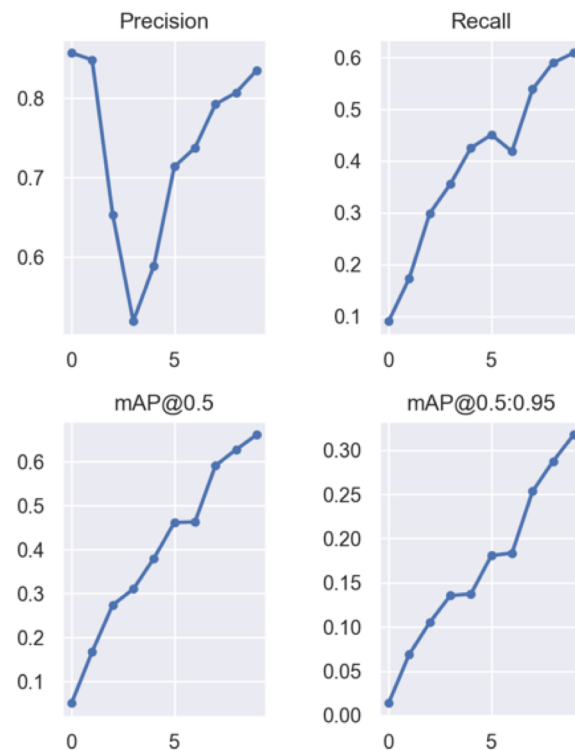
Yolo v7

Train : 5000 筆; Val : 600 筆; Epoch : 10; Batch size : 32

Model summary : 415 layers; 37,223,526 parameters; 105.2 GFLOPS

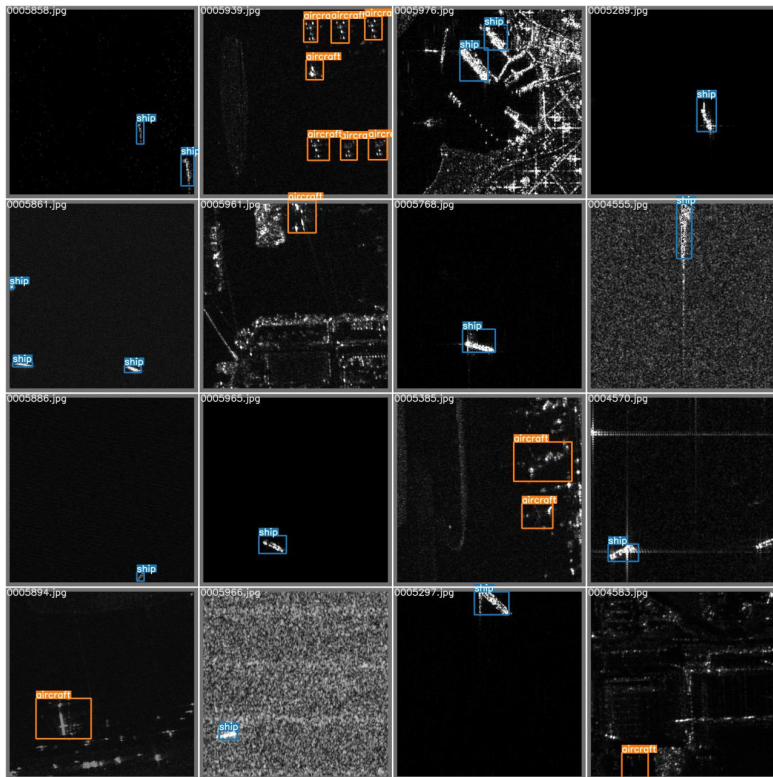
Epoch	gpu_mem	box	obj	cls	total	labels	img_size
6/9	23.6G	0.04416	0.006385	0.003363	0.05391	26	640: 100% 157/157 [30:35<00:00, 11.69s/
Class		Images	Labels	P	R	mAP@.5	mAP@.5:.95: 100% 10/10 [00:52<00:0
all		600	1217	0.737	0.418	0.463	0.184
Epoch	gpu_mem	box	obj	cls	total	labels	img_size
7/9	23.6G	0.04337	0.006352	0.003193	0.05292	27	640: 100% 157/157 [30:19<00:00, 11.59s/
Class		Images	Labels	P	R	mAP@.5	mAP@.5:.95: 100% 10/10 [00:52<00:0
all		600	1217	0.792	0.539	0.591	0.253
Epoch	gpu_mem	box	obj	cls	total	labels	img_size
8/9	23.6G	0.04107	0.006157	0.002308	0.04954	20	640: 100% 157/157 [30:19<00:00, 11.59s/
Class		Images	Labels	P	R	mAP@.5	mAP@.5:.95: 100% 10/10 [00:52<00:0
all		600	1217	0.807	0.59	0.627	0.287
Epoch	gpu_mem	box	obj	cls	total	labels	img_size
9/9	23.6G	0.03958	0.005864	0.001797	0.04724	19	640: 100% 157/157 [30:10<00:00, 11.53s/
Class		Images	Labels	P	R	mAP@.5	mAP@.5:.95: 100% 10/10 [00:55<00:0
all		600	1217	0.835	0.609	0.661	0.317
ship		600	719	0.805	0.782	0.838	0.422
aircraft		600	353	0.743	0.581	0.679	0.299
car		600	35	0.804	0.743	0.83	0.484
tank		600	104	0.823	0.938	0.93	0.373
bridge		600	6	1	0	0.027	0.00873

10 epochs completed in 5.265 hours.

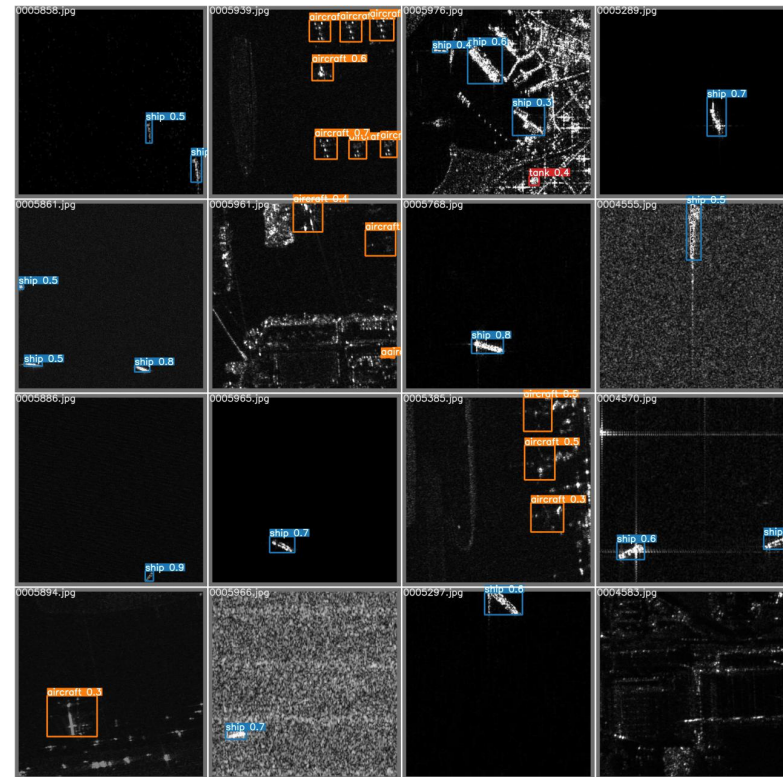


Yolo v7

Ground truth



pred



Yolo v7x

Train : 5000 筆; Val : 600 筆; Epoch : 10; Batch size : 24

Model summary : 467 layers; 70,848,782 parameters; 189.0 GFLOPS

```
Epoch 6/9  gpu_mem 21.8G  box 0.04412  obj 0.006602  cls 0.003416  total 0.05414  labels 38  img_size 640: 100% 209/209 [39:49<00:00, 11.43s/
Class      Images  Labels  P      R      mAP@.5  mAP@.5: .95: 100% 13/13 [01:33<00:0
all        600    1217   0.788  0.458  0.545   0.233

Epoch 7/9  gpu_mem 21.8G  box 0.04176  obj 0.006288  cls 0.002428  total 0.05047  labels 25  img_size 640: 100% 209/209 [38:56<00:00, 11.18s/
Class      Images  Labels  P      R      mAP@.5  mAP@.5: .95: 100% 13/13 [01:33<00:0
all        600    1217   0.811  0.55   0.625   0.304

Epoch 8/9  gpu_mem 21.8G  box 0.04018  obj 0.006237  cls 0.002315  total 0.04873  labels 25  img_size 640: 100% 209/209 [36:32<00:00, 10.49s/
Class      Images  Labels  P      R      mAP@.5  mAP@.5: .95: 100% 13/13 [01:32<00:0
all        600    1217   0.855  0.52   0.609   0.283

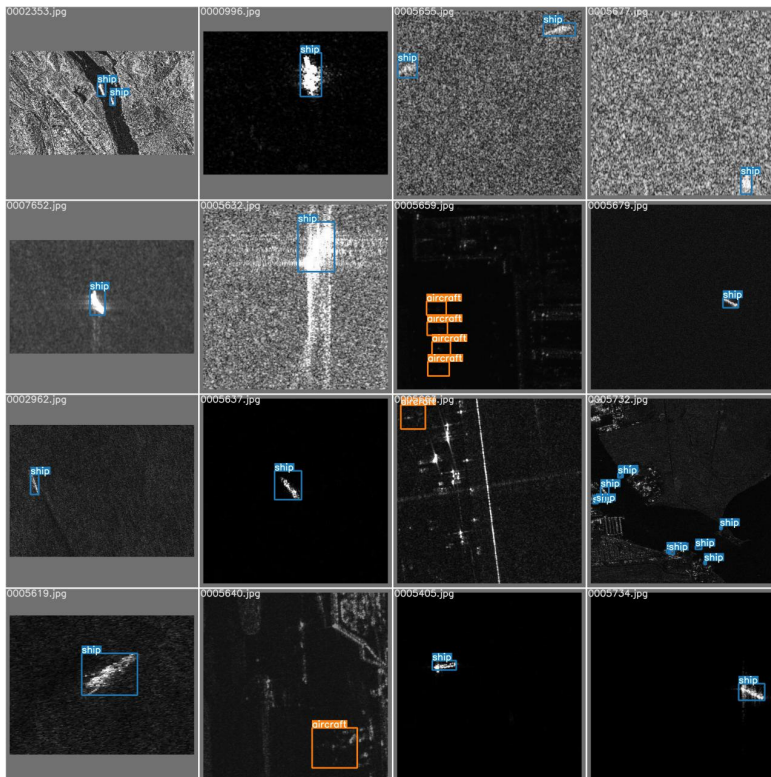
Epoch 9/9  gpu_mem 21.8G  box 0.03899  obj 0.006068  cls 0.001791  total 0.04685  labels 23  img_size 640: 100% 209/209 [36:25<00:00, 10.45s/
Class      Images  Labels  P      R      mAP@.5  mAP@.5: .95: 100% 13/13 [01:37<00:0
all        600    1217   0.833  0.601  0.659   0.305
ship       600    719    0.776  0.79   0.829   0.418
aircraft   600    353    0.815  0.587  0.753   0.335
car        600    35     0.706  0.771  0.79    0.444
tank       600    104    0.866  0.856  0.911   0.328
bridge     600    6      1      0      0.012   0.00216

10 epochs completed in 6.525 hours.
```

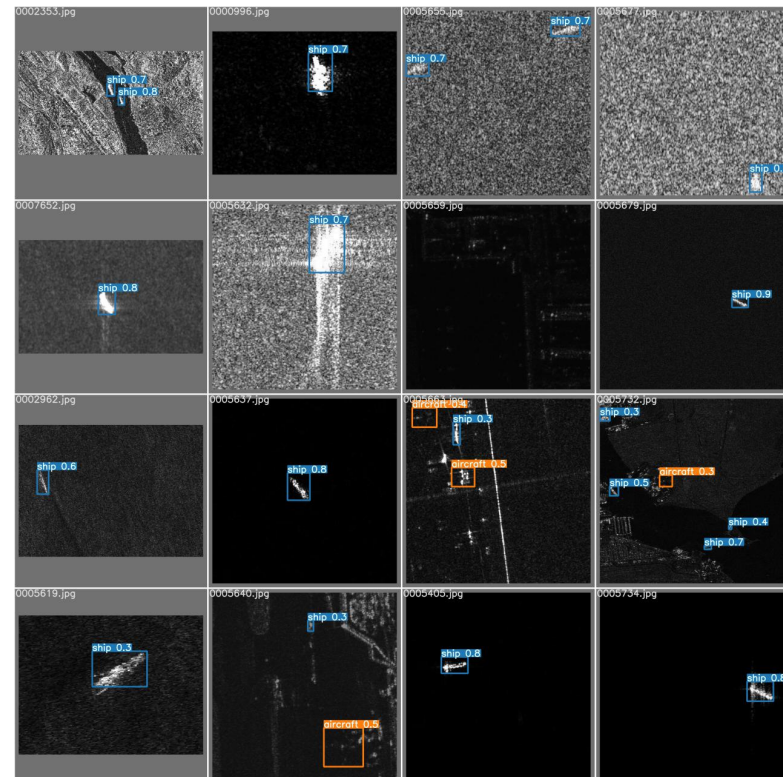


Yolo v7x

Ground truth



pred



PRB-FPB-CSP

Train : 5000 筆; Val : 600 筆; Epoch : 15; Batch size : 24
 Model summary : 698 layers; 61,303,171 parameters; 153.3 GFLOPS

```

Epoch  gpu_mem  box  obj  cls  total  labels  img_size
0/4      8.99G  0.05304 0.008204 0.01113 0.07238 15 640: 100%|█ 209/209 [1:45:57<00:00, 30.42
Class   Images  Labels  P      R      mAP@.5  mAP@.5:.95: 100%|█ 13/13 [00:16<00:0
all     600     1217   0.547  0.133  0.171   0.0744

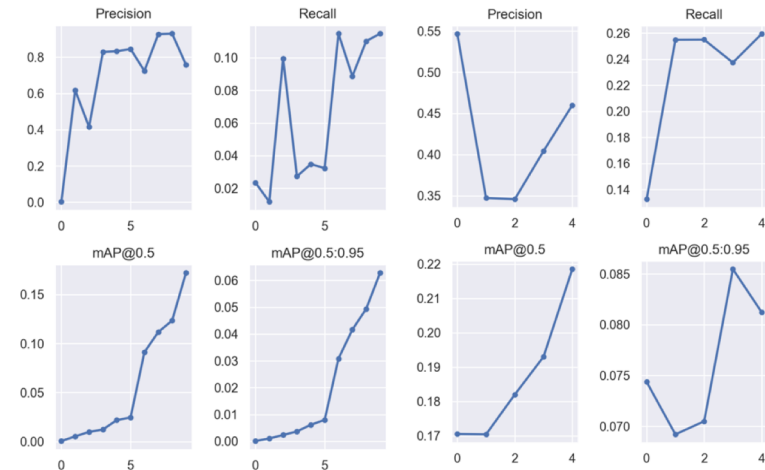
Epoch  gpu_mem  box  obj  cls  total  labels  img_size
1/4      21G    0.05262 0.00825  0.0107  0.07157 39 640: 100%|█ 209/209 [1:23:43<00:00, 24.03
Class   Images  Labels  P      R      mAP@.5  mAP@.5:.95: 100%|█ 13/13 [01:32<00:0
all     600     1217   0.347  0.255  0.17    0.0692

Epoch  gpu_mem  box  obj  cls  total  labels  img_size
2/4      21G    0.05313 0.008046 0.01006 0.07124 24 640: 100%|█ 209/209 [1:10:10<00:00, 20.14
Class   Images  Labels  P      R      mAP@.5  mAP@.5:.95: 100%|█ 13/13 [01:33<00:0
all     600     1217   0.346  0.255  0.182   0.0705

Epoch  gpu_mem  box  obj  cls  total  labels  img_size
3/4      21G    0.05265 0.007977 0.01038 0.071  25 640: 100%|█ 209/209 [1:13:16<00:00, 21.04
Class   Images  Labels  P      R      mAP@.5  mAP@.5:.95: 100%|█ 13/13 [01:34<00:0
all     600     1217   0.404  0.237  0.193   0.0855

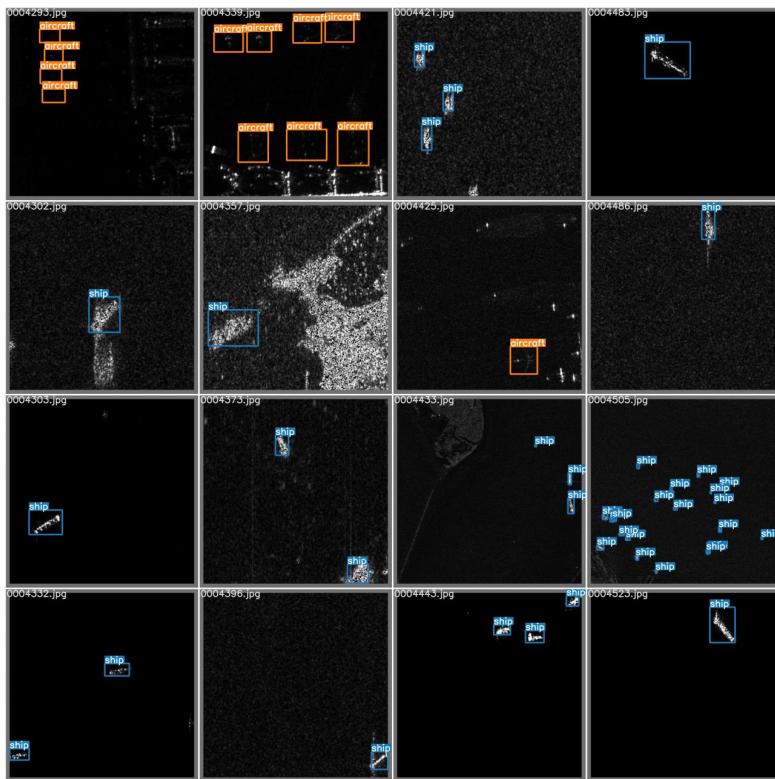
Epoch  gpu_mem  box  obj  cls  total  labels  img_size
4/4      21G    0.05187 0.00784  0.01008 0.06979 17 640: 100%|█ 209/209 [1:06:08<00:00, 18.99
Class   Images  Labels  P      R      mAP@.5  mAP@.5:.95: 100%|█ 13/13 [01:35<00:0
all     600     1217   0.46   0.259  0.218   0.0812
ship    600     719    0.314  0.807  0.701   0.265
aircraft 600     353    0.224  0.266  0.157   0.0407
car     600     35     0.704  0.137  0.193   0.0896
tank    600     104    0.0578 0.0865 0.0191  0.00666
bridge  600     6       1       0       0.0219  0.00438

5 epochs completed in 6.768 hours.
  
```

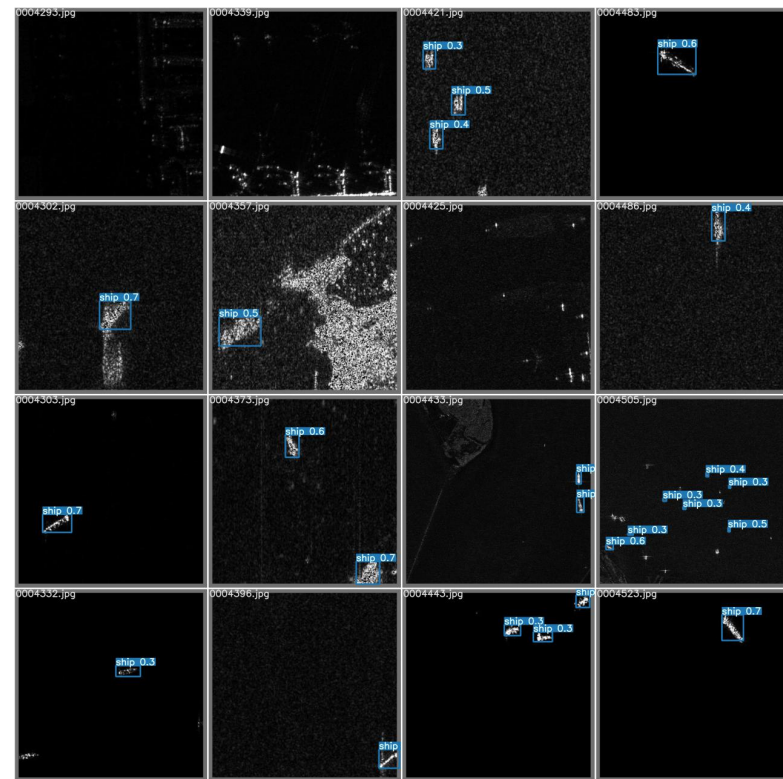


PRB-FPB-CSP

Ground truth



pred



• 結果討論

- YOLOv7 與 YOLOv7x 表現差不多，且與原始論文相比在 mAP 上表現較佳
- PRB-FPN 表現較差，可能原因：
 1. YOLOv7 有 pretrain weight，但 PRB-FPN 直接以初始權重作訓練
 2. PRB-FPN 主要用於自駕車魚眼，可能不適合 SAR Image

- PRB-FPN 在船隻判別上較 YOLO 為佳

Table 4: Comparison of different pretrain strategies using Faster-RCNN and Res50 as the detection model.

ID	Model Input	Pretrain			mAP ↑
		Multi-stage	Dataset	Component	
1	SAR (Raw pixels)	✗	ImageNet	Backbone	49.0
2		✓	ImageNet + DIOR	Framework	49.5
3		✓	ImageNet + DOTA	Backbone	49.3
4				Framework	50.2

[Yuxuan Li et al., 2024]

- 遇到困難點

- 背景知識不足
- 資料量過大難以處理
- 理解目標花費時間較多
- 實作方面

• 未來展望

- 將所有資料執行訓練
- 嘗試其他特徵處理
- PRB-FPN先進行預訓練